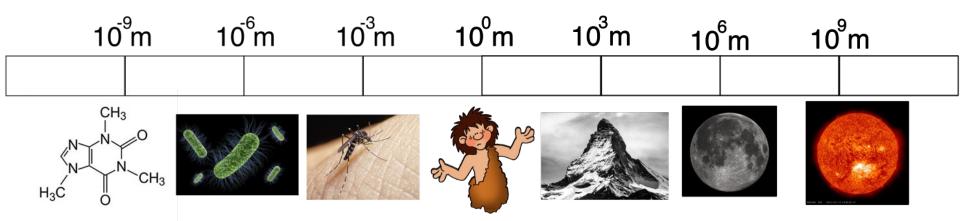


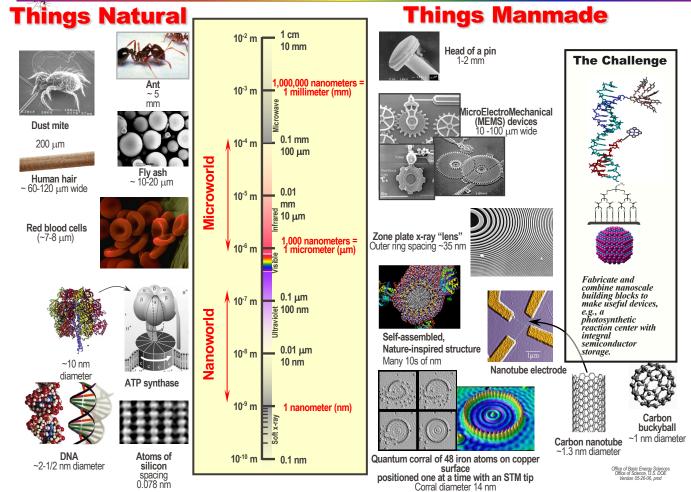
 École polytechnique fédérale de Lausanne



Why we need nanoscale microscopy



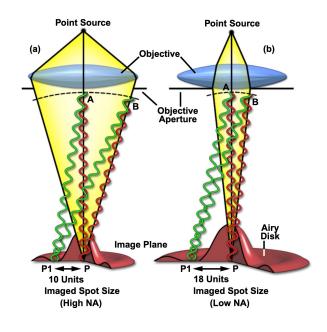
The Scale of Things - Nanometers and More



EPFL Why is it difficult to measure small things? The diffraction limit

In any (far field) microscopy system where we create a magnified image of an object via an image projection using diffractive elements (such as lenses) we run into the *diffraction limit*:

Point sources (with zero size) are projected to an Airy disk with a certain size. Two-point sources that are close together will result in two Airy disks close together. If the disks are too close together, they can no longer be separated based on their intensity. That is then the resolution limit of the microscope.



ļ

What determines the achievable resolution

Abbe Resolution_{x,y} =
$$\frac{\lambda}{2NA}$$

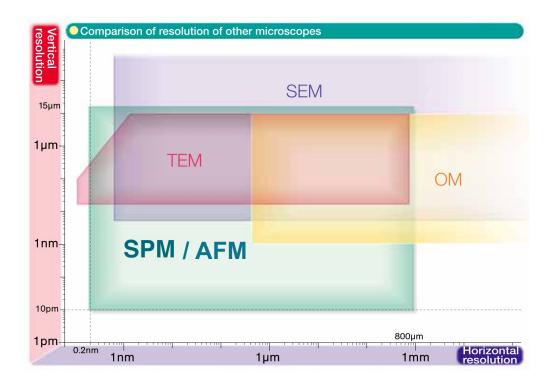
- λ... wavelength
- NA ... numerical aperture

What can we do to get around this?

- Work with smaller wavelengths: instead of photons use particles with much smaller wavelength (such as electrons: de Broglie wavelength of an electron with acceleration voltage of $10kV = 1,22 \cdot 10^{-11}m$, which is 40'000 times smaller than that of a photon). That is what we use in electron microscopy
- Try to use non far field microscopy techniques (near field techniques or scanning probe techniques). This is what we do in atomic force microscopy (AFM), scanning tunneling microscopy (STM) or scanning near field optical microscopy (SNOM)

Resolution is NOT everything...

...but it's sure nice to have a good one



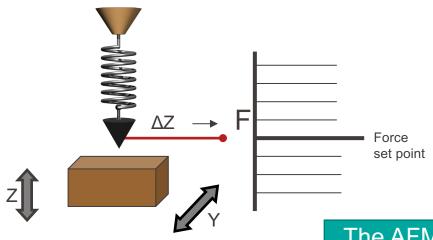
6



What is an AFM?

(don't be fooled by the word *atomic*)

"Scanning force microscopy" SFM



The AFM measures the effect of forces acting on the sharp tip on a spring as a function of the position on the surface. – <u>sometimes</u> these forces are due to topography



It all started with *Tunneling...*

- Binnig, Gerber, Rohrer, Wiebel Tunneling through a controller vacuum gap.(Applied Physics Letters 40, 178 (1982)
- "This investigation is the first step towards the development of scanning tunneling microscopy, where the surface is scanned by a tunnel current and should open the door to a new area of surface studies."



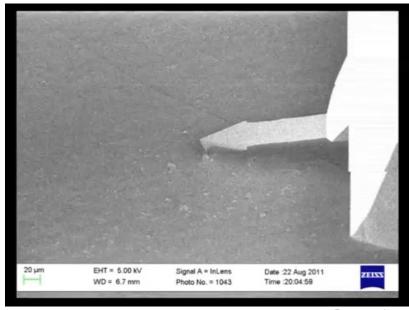


Scanning tunnelling microscopy was invented by Gerd Binnig (right) and Heinrich Rohrer (left) in 1981. They were awarded the Nobel Prize in 1986.

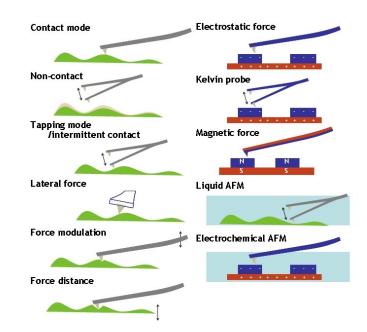
...but only for conducting samples!



Atomic force microscopy (AFM)

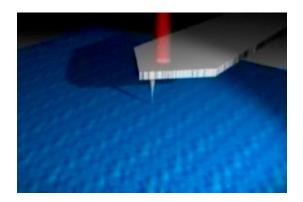


From www.zeiss.com



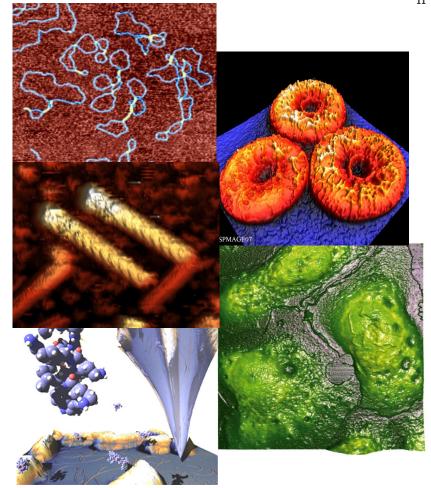


Atomic force microscopy



A versatile tool for nanoscale measurements...

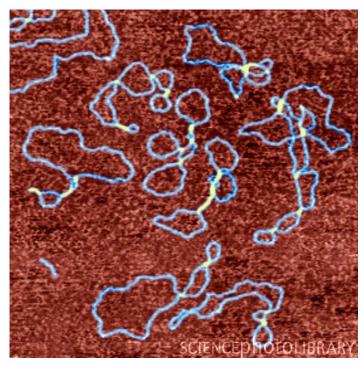
- Single molecule resolution
- High resolution imaging in aqueous solution
- Nanomanipulation
- Single molecule mechanics
- Imaging of living cells





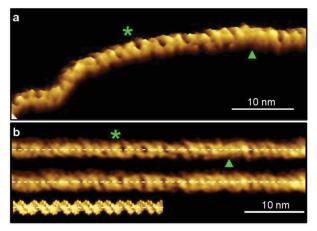
Single molecule resolution

Plasmid DNA on mica



Source: SciencePhotoLibrary

- Single molecules can be easily resolved
- Even the double helix!

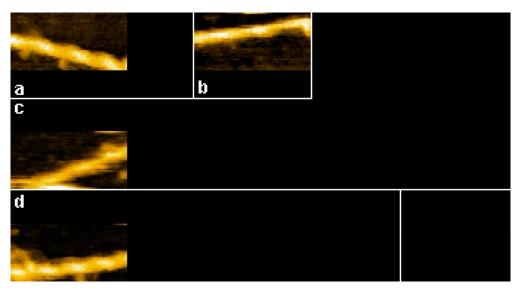


Pyne et al. Small, 10, Nr16, 2014



Single molecule resolution

Walking myosin V on actin fibers

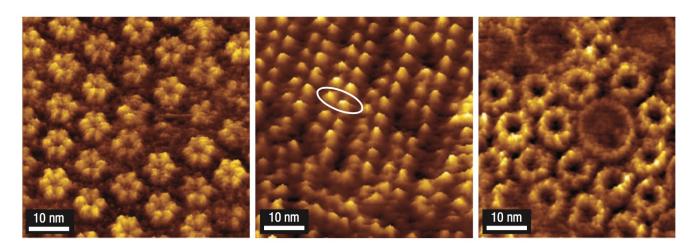


Nature 468, 72 (2010)



High resolution images in fluid of proteins

- Imaging of membranes and membrane bound proteins
- Imaging of live cells



From Review Nature Nanotechnology 2008, D. Müller and I. Dufren,



AFM can be used for nanomanipulation



Image from: http://www.veeco.com/library/nanotheater

- AFM patterning of a silicon surface using anodic oxidation
- Other approaches have been developed such as
 - · dip-pen nanolithography and
 - Thermal scanning probe lithography (tSPL)

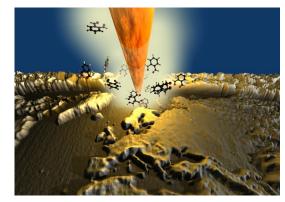


Image from: https://www.swisslitho.com

Different types of scanning probe microscopes

- SPM = scanning probe microscopy
- AFM= Atomic force microscopy (AFM), also known as
- SFM =scanning force microscopy
- STM scanning tunneling microscopy
- ...
- SSETM = scanning single-Electron transistor microscopy

Wikipedia lists 41 different SPM modes!

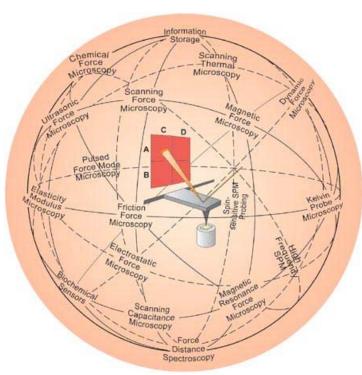
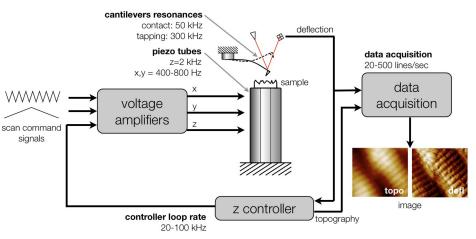


image: Christoph Gerber; copyright Nature Publishing Group

EPFL What's in an AFM?



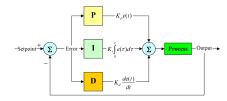
Photodiode (PSD)

- Converts light into an electrical current
- It will detect the cantilever deflection

Piezo Element that moves the sample in XYZ by applying a voltage

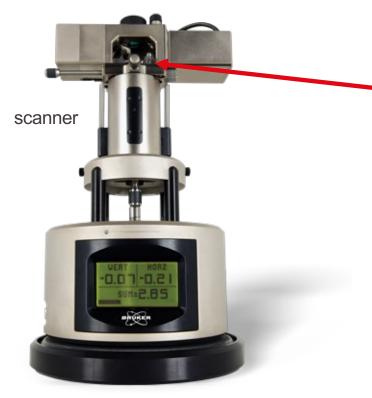
Feedback loop

A feedback system is one in which the output signal is sampled and then fed back to the input to form an error signal that drives the system

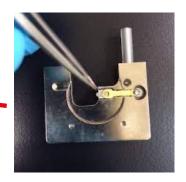


What's in an AFM?

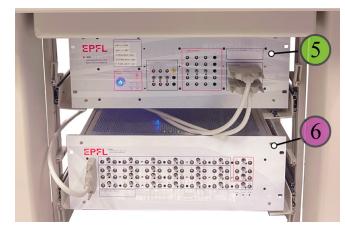




cantilever holder



controller and HV amplifier





A few principles we should understand

- Optical lever detection
- Piezo-scanners
- Feedback/setpoint
- Force curves
- Imaging modes



Optical lever detection

Transduces cantilever deflection into a voltage

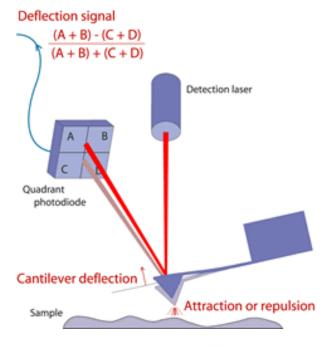
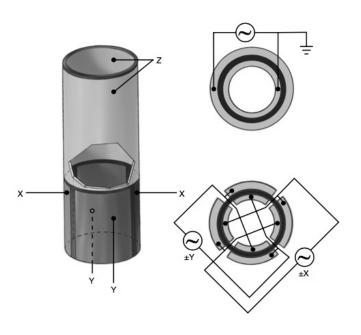


Image source: http://usa.jpk.com

- A very sensitive way to measure cantilever <u>angle change</u>
- The change of angle is amplified by the distance from the cantilever tip to the 4-quadrant photodiode
- Each quadrant creates a current which is turned into a voltage using a transimpedance amplifier (I/V converter)
- The cantilever deflection is the <u>normalized</u> difference of the top quadrants minus the bottom quadrants

Piezo scanners

Piezo materials expand when a voltage is applied



Piezo scanners can be:

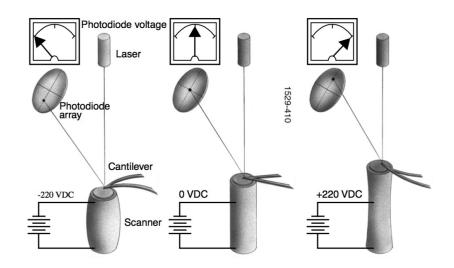
- Tubes
- Stacks
- Plates
- Monolythic piezo blocks

Or other types of actuation can be used:

- Voice coil actuation
- Electrostatic combs
- Linear magnetic motors

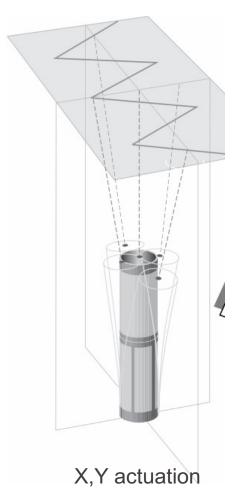
Piezo scanners

Piezo materials expand when a voltage is applied



Z actuation

Images: Bruker Multimode Manual

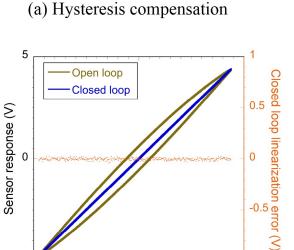




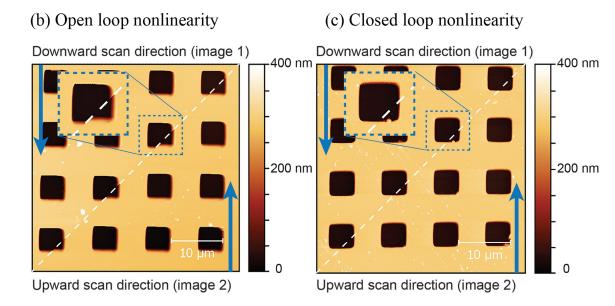
-5

Problems with piezo actuators

Hysteresis



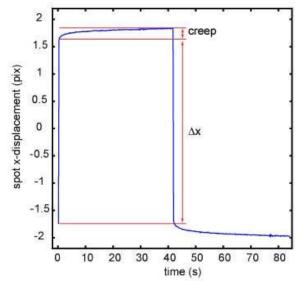
0 Reference (V)

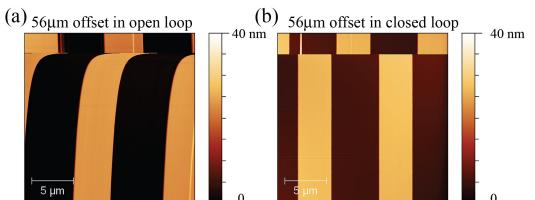


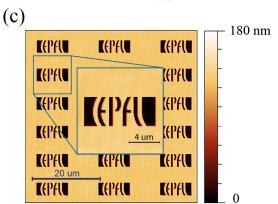
Problems with piezo actuators

Creep

- The piezo only moves ca 90% of the requested distance right away. The rest of the way it creeps very slowly!
- This causes image artefacts like distortion



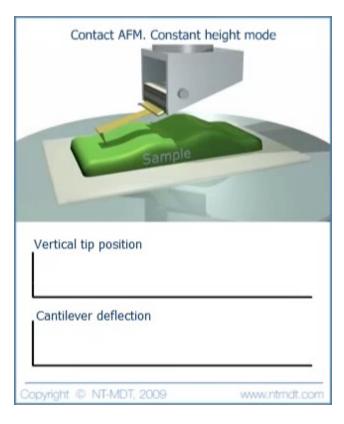






Why do we need feedback?

Constant height mode

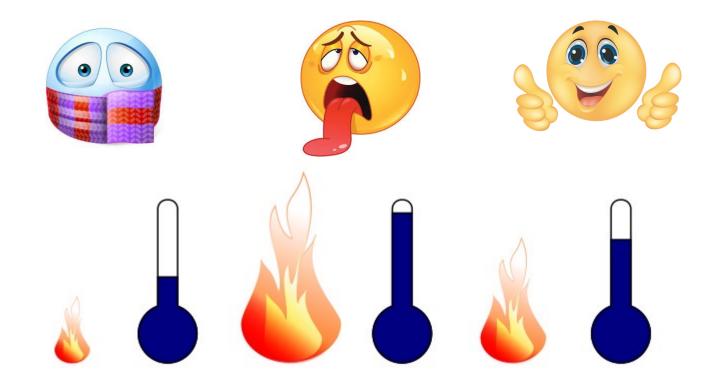


Why don't we just drag the cantilever over the surface?

- Cantilever deflection is not linear → height measurement is distorted
- Force on cantilever is not constant
 - → tip and sample can get damaged

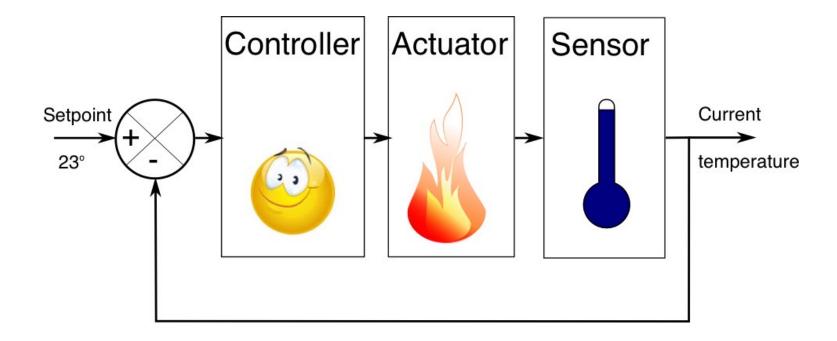


What do you do if you are cold?



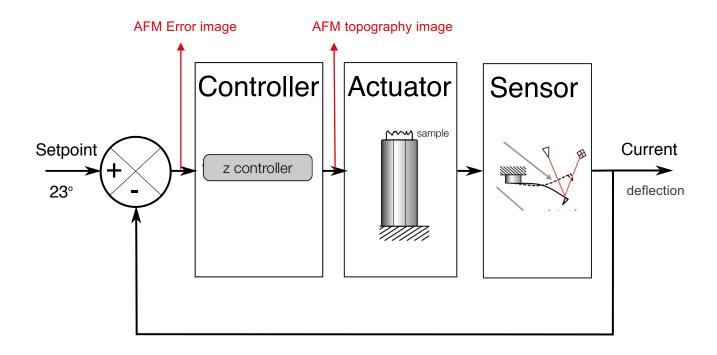


Rearranging into a feedback loop



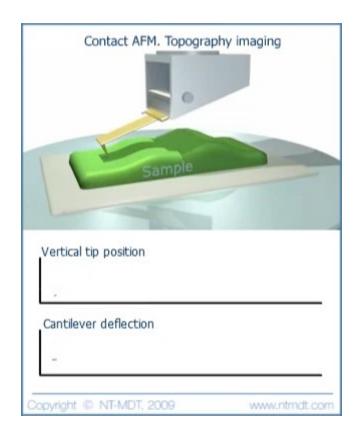


Rearranging into a feedback loop





Feedback keeps the tip/sample interaction constant

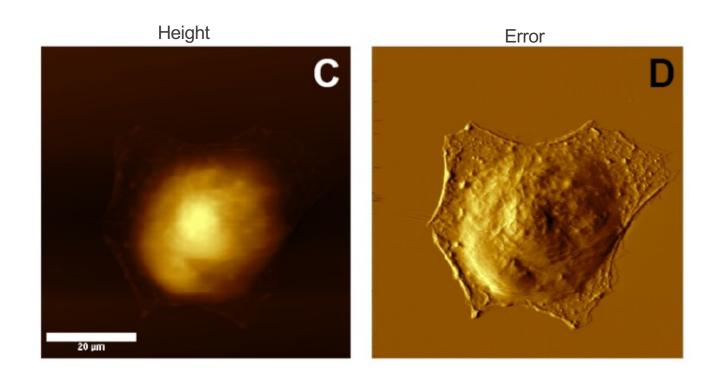


Benefits of operating in feedback:

- Cantilever deflection varies only slightly around setpoint
- The amount that the controller has to move the piezo up or down approximates the topography of the sample



Height image vs error image





What is the meaning of the error signal?

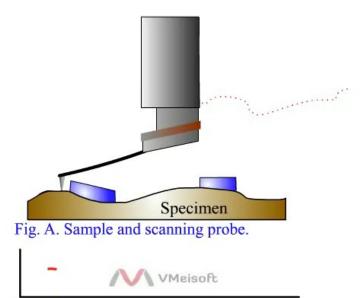


Fig. B. Profile of scanner moving.

Fig. C. Profile of cantilever deflection changing.

- The deflection/error signal is as much part of the AFM image as the topography image (also called height image)!
- It accentuates edges and features with small spatial frequencies
- The height image combined with the error image represent the "true topography"



Tip sample interactions

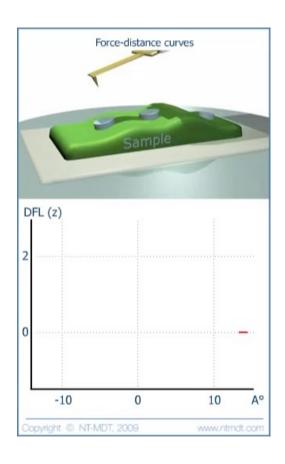
Force curves

There are many forces that can act between the tip and the sample

- Van Der Waals forces (attractive)
- Pauli repulsion (repulsive)
- Electrostatic forces (attractive or repulsive)
- Capillary forces (attractive)
- Magnetic forces (attractive or repulsive)
- . . .

We can measure what forces act on a cantilever as a function of distance from the surface by measuring a *Force curve*

Force curves



Force curves can tell us a lot about the tip sample interaction:

- What is the adhesion of tip to sample
- What is the hardness of the sample
- What is the energy dissipation per cycle

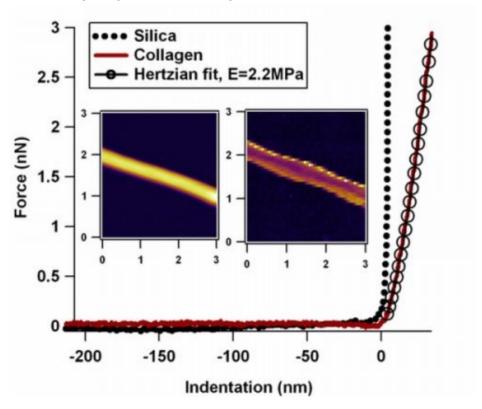
Or about our measurement setup

 What is the deflection sensitivity (how many nm do we have to deflect the cantilever to measure 1V shift in the 4-quadrant photodiode)



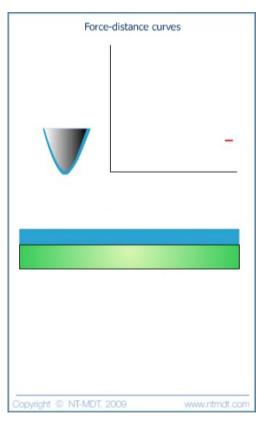
Force volume mode

Creating mechanical properties maps



Surface adhesion

Capillary forces are always present when imaging in air!



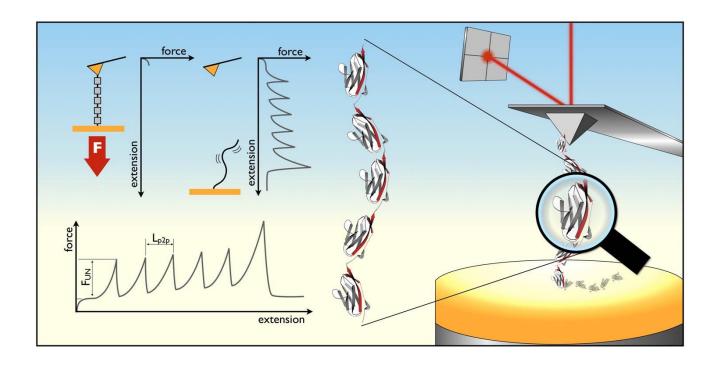
All surfaces in ambient are covered with a thin water layer.

- Capillary forces act between tip and surface
- When imaging in air they create a "snap-in" as well as adhesion
- They can lead to many artefacts and instabilities



Single molecule force spectroscopy

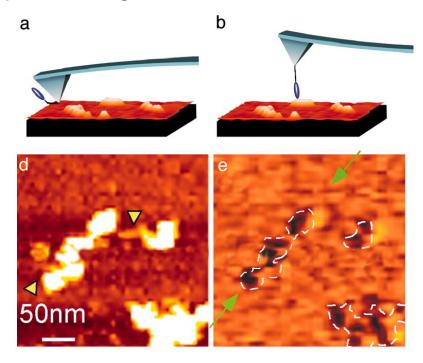
Force curves as a tool for single molecule mechanics





Single molecule recognition imaging

Detecting specific antigens on a surface





Dynamic modes

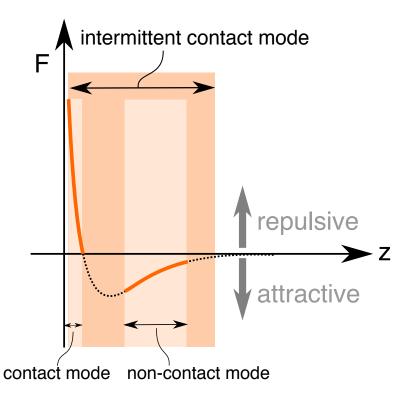
Reduces tip sample interactions

- Tapping mode™ (intermittent contact mode, amplitude modulation mode, dynamic mode,...)
- Non-contact mode

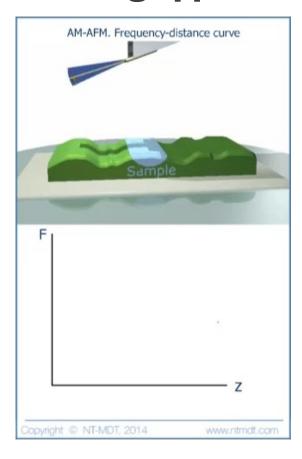
Off resonance modes (Peak Force Tapping[™], QI mode[™], hopping mode[™],
 HybriD mode[™],...)

Lennard-Jones potential

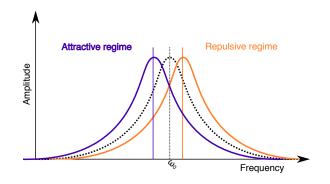
The cantilever feels different force regimes



Oscillating approach curves



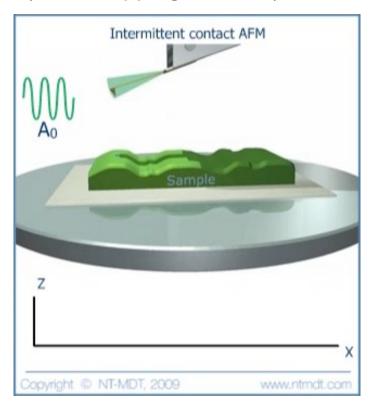
- As the cantilever approaches the surface it feels different forces (due to the Lennard-Jones potential)
- When the cantilever is in the <u>attractive regime</u> the <u>resonance</u> <u>frequency decreases</u>
- When the cantilever is in the <u>repulsive regime</u> the <u>resonance</u> <u>frequency increases</u>



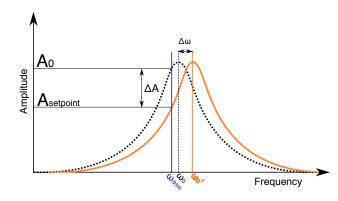


Amplitude modulation

(a.k.a. Tapping mode™)

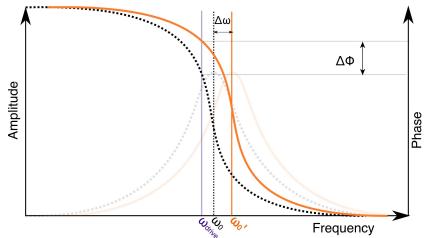


- In tapping mode we excite the cantilever at a fixed frequency ω_{drive} slightly below its resonance frequency
- As the cantilever approaches into the repulsive regime, the resonance frequency (of cantilever + sample force) increases.
- At the fixed frequency ω, the resulting amplitude will therefore drop as we enter the repulsive regime
- The amplitude error is used for the feedback parameter



Phase imaging

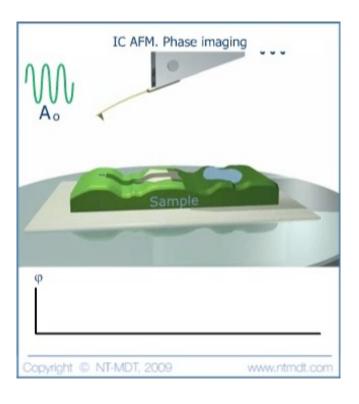
In tapping mode



- The phase difference <u>between the cantilever drive signal</u> and the <u>cantilever oscillation</u> is called the "phase signal"
- The resonance shift $\Delta\omega$ also introduces a phase shift $\Delta\phi$ at the driving frequency ω_{drive}
- This shift could also be used for feedback, but...
- ... other factors such as materials properties affect phase as well

Phase imaging

In tapping mode can give materials contrast



- In tapping mode, the phase channel is an additional observable channel
- If no topography is present, the phase signal can be used to distinguish materials properties
- But beware of <u>interpretation artefacts!</u>



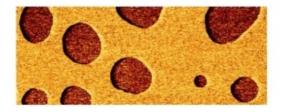
Height vs Amplitude vs Phase



Height



Amplitude (error signal)

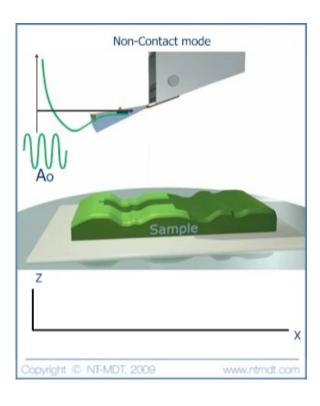


Phase shift

Lipid phase contrast from intermittent contact mode AFM in liquid, 18 x 7 micrometer area. The height (top) and phase (bottom) images show contrast between the lipid phases. The amplitude image (center) shows contrast at the edges of the patches.

Non-contact mode

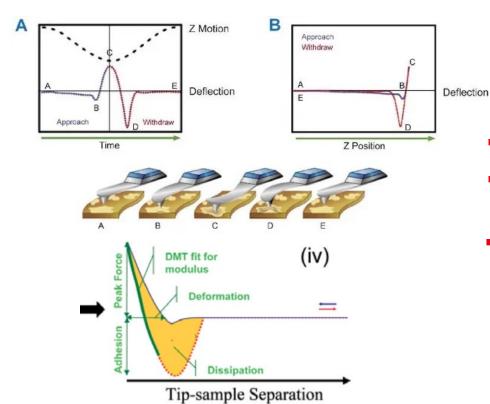
Imaging in the attractive regime



- In non-contact mode, the cantilever "never touches" the surface
- Non-contact mode is <u>difficult to maintain</u> due to the low forces and small force gradients
- Primarily used in vacuum

Off-resonance modes

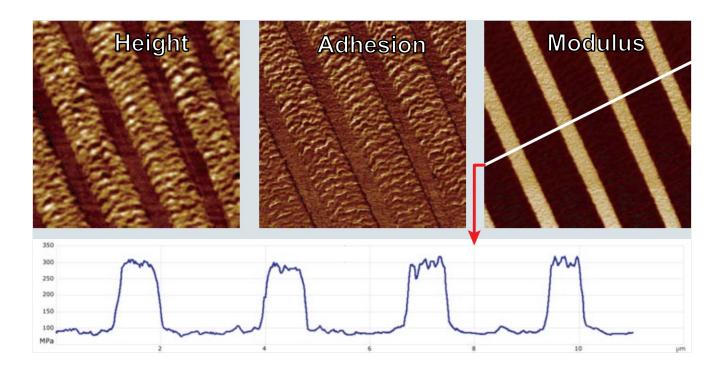
Peak Force Tapping, QI mode, hopping mode, HybriD mode,...



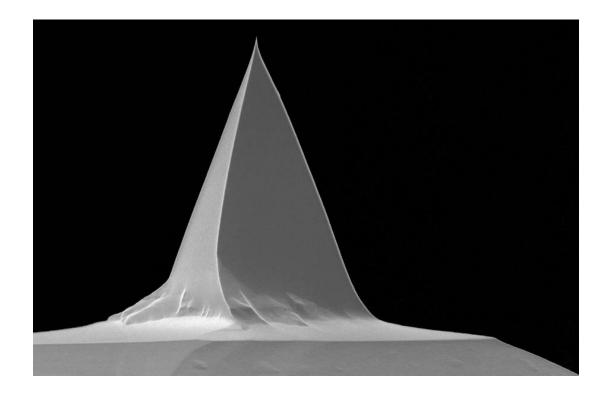
- Ramp often done sinusoidally
- After baseline correction a force curve for each pixel is extracted
- Data extracted from the force curve:
 - Elastic modulus
 - Adhesion
 - Indentation
 - Energy dissipation

Measuring multiple sample properties

Multilayer polymer optical film

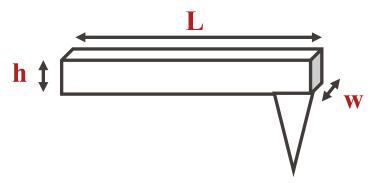


The cantilever



Cantilevers

What considerations govern the probe dimensions?



Resonance frequency

Normal spring constant

$$\mathbf{F}_{\mathbf{R}} \cong 0.162 \sqrt{\frac{\mathbf{E}}{\rho}} \bullet \frac{\mathbf{h}}{\mathbf{L}^2}$$

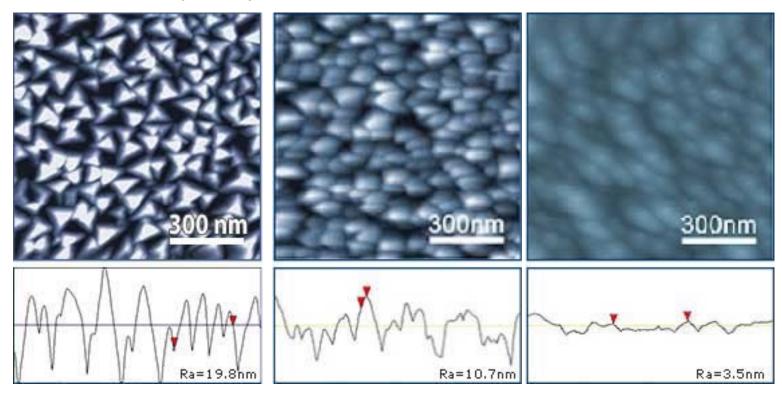
$$\mathbf{k_N} = \frac{\mathbf{Ewh}^3}{4\mathbf{L}^3}$$

E= Young's modulus, ρ = density

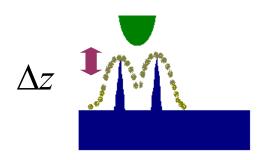


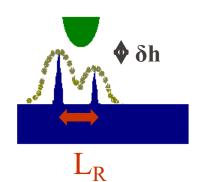
Image resolution

Influence of tip sharpness



Resolution depends on...





- Resolution depends on:
 - Instrument noise floor (Δz)
 - Tip radius (R)
 - Sample topography (δh)

$$L_R = \sqrt{2R} \left(\sqrt{\Delta z} + \sqrt{\delta h + \Delta z} \right)$$

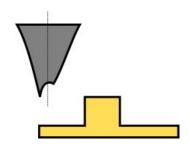
If the sample is compliant the resolution is even further reduced by the indentation (I):

$$l = 2 \left[\frac{3RF}{4E^*} \right]^{\frac{1}{3}}$$



Tip artefacts

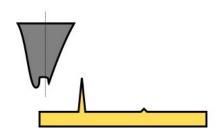
Draw the height profile the tip would measure





Tip artefacts

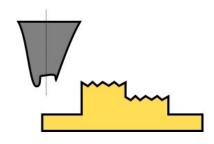
Draw the height profile the tip would measure





Tip artefacts

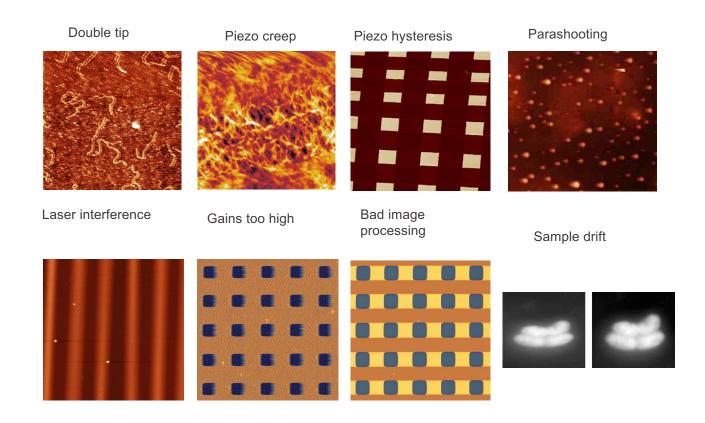
Draw the height profile the tip would measure





AFM image artefacts

Always be critical when interpreting your AFM images!



EPFL Questions?

